

Theorem (No proof) The functions  $h_n(x) = H_n(x) e^{-x^2/2}$  for  $n = 0, 1, 2, \dots$  are all the eigenfunctions of the Fourier Transform. = complete orthogonal system (Diagonalization of F.T. in this co-dim. space).

## LAPLACE TRANSFORM (Chapter V)

It is a sort of Fourier Transform on a half-line  $[0; +\infty)$ .

Def. We say that  $f(t) \in E$  if  $f(t) = 0$  for  $t < 0$  and  $\exists \alpha \in \mathbb{R}$  such that

- (1)  $f(t) e^{-\alpha t}$  in  $L^1([0; +\infty))$ ; piecewise
- (2)  $C^1(\mathbb{R})$ ; (3)  $f(x) = \frac{f(x+) + f(x-)}{2}$  for each real number  $x$ .



Def.

$$\mathcal{L}[f](s) = \int_0^{+\infty} f(t) e^{-st} dt$$

$$(s \in \mathbb{C}) = \int_0^{+\infty} f(t) e^{-\sigma t} (\cos \omega t - i \sin \omega t) dt$$

Tradition  $s = \sigma + i\omega \in \mathbb{C}$  ( $\sigma = \text{Re}(s)$ ;  $\omega = \text{Im}(s)$ )

ex.  $f(t) = e^{at}$  where  $a = b + ic \in \mathbb{C}$

$$\mathcal{L}(f) = F(s)$$

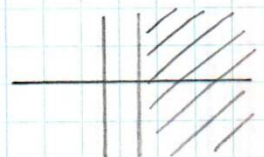
(Notation)

The original function has real variable, the transform a complex one

$$\mathcal{L}(f) = F(s) = \int_0^{\infty} e^{at} e^{-st} dt = \int_0^{\infty} e^{-(s-a)t} dt$$

It's easy to see that this integral converges  $\Leftrightarrow \text{Re}(s) > \text{Re}(a)$

$$= \left[ \frac{e^{-(s-a)t}}{-(s-a)} \right]_{t=0}^{t=\infty} = \frac{1}{s-a}$$





Remarks The original function  $f(t) = e^{at}$  is  $f: \mathbb{R} \rightarrow \mathbb{C}$   
(in particular is a function of a real variable  $t$ )  
(also  $f(t)$  itself could be real).

The transform function  $F(s)$  is a  $F: \mathbb{C} \rightarrow \mathbb{C}$   
This function is also holomorphic except for a finite  
number of singularities.

In the case of this example, the only singularity is  
at  $s = a$  (simple pole, where DEN = 0)

Holomorphic: locally can be written with a complex  
power series (Taylor Series) with radius  $R > 0$ ;  
equivalently, the complex derivative exists finite

$$\lim_{h \rightarrow 0} \frac{F(s+h) - F(s)}{h} = F'(s)$$

Analytic continuation: the integral that defines the  
holomorphic function  $F(s)$  is well defined only in a  
half-plane ( $\operatorname{Re}(s) > \operatorname{Re}(a)$ ) BUT the function  $F(s)$  itself  
can be (easily or not, depending on cases) analytically  
continued to all  $\mathbb{C} \setminus \{\text{finite set of singularities}\}$

This pattern, that we have already seen in the  
simple case  $f(t) = e^{at}$ , actually holds in general  
if  $f(t) \in E$ .

Laplace Transform

Linearity  $\mathcal{L}(\alpha f(t) + \beta g(t)) = \alpha \mathcal{L}(f)(s) + \beta \mathcal{L}(g)(s) =$   
 $= \alpha F(s) + \beta G(s)$



ex.1) using linearity compute  $\mathcal{L}(\sin at)$  and exponentials

N.B. When we say  $\mathcal{L}(\sin at)$  what we mean is

$$\mathcal{L}(f(t)) \text{ where } f(t) = \begin{cases} 0 & \text{if } t < 0 \\ \sin at & \text{if } t \geq 0 \end{cases}$$

$$\sin at \stackrel{\text{Euler's}}{=} \frac{e^{iat} - e^{-iat}}{2i}$$

We use the previous:

$$\mathcal{L}(\sin at) = \frac{1}{2i} \mathcal{L}(e^{iat}) - \frac{1}{2i} \mathcal{L}(e^{-iat}) \quad \mathcal{L}(e^{at}) = \frac{1}{s-a}$$

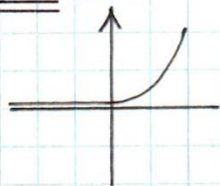
$$= \frac{1}{2i} \left\{ \frac{1}{s-ia} - \frac{1}{s+ia} \right\} = \frac{1}{2i} \frac{\cancel{s+ia} - (\cancel{s-ia})}{(s^2 - (ia)^2)} = \frac{2ia}{2i(s^2 + a^2)} =$$

$$= \frac{a}{s^2 + a^2}$$

$$\underline{\text{ex.2})} \quad \mathcal{L}(\cos at) \stackrel{\text{Euler's}}{=} \mathcal{L}\left(\frac{e^{iat} + e^{-iat}}{2}\right) = \frac{1}{2} \left\{ \frac{1}{s-ia} + \frac{1}{s+ia} \right\} =$$

$$= \frac{1}{2} \frac{\cancel{s+ia} + (\cancel{s-ia})}{(s^2 + a^2)} = \frac{s}{s^2 + a^2}$$

ex.3)



$$\mathcal{L}(t^2) = \int_0^{+\infty} t^2 e^{-st} dt \stackrel{\text{b.p.}}{=} \int_0^{+\infty} f(t) e^{-st} dt$$

$$f(t) = \begin{cases} 0 & \text{for } t < 0 \\ t^2 & \text{for } t \geq 0 \end{cases}$$

$$= \left[ \frac{t^2 e^{-st}}{-s} \right]_0^{+\infty} + \int_0^{+\infty} \frac{e^{-st}}{+s} 2t dt =$$

$$= 0 + \frac{2}{s} \int_0^{+\infty} t \underbrace{e^{-st} dt}_{d\left(\frac{e^{-st}}{-s}\right)} = + \frac{2}{s} \left\{ \left[ t \frac{e^{-st}}{-s} \right]_0^{+\infty} + \int_0^{+\infty} \frac{e^{-st}}{-s} dt \right\} =$$

$$+ \frac{2}{s^2} \int_0^{+\infty} e^{-st} dt =$$

$$= + \frac{2}{s^2} \left[ \frac{e^{-st}}{-s} \right]_0^{+\infty} = \frac{2}{s^3}$$



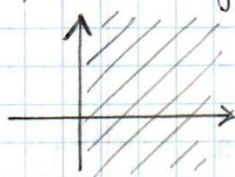
More generally, using  $n$  integrations by parts, we get  $\mathcal{L}(t^n) = \frac{n!}{s^{n+1}}$

Put this in a table and then by linearity is easy to do

the  $\mathcal{L}$ (polynomials). Actually using  $\Gamma$  function we can also compute  $\mathcal{L}(t^\alpha)$ ,  $\alpha \in \mathbb{R}$

Def.  $\Gamma(\alpha+1) = \int_0^{+\infty} t^\alpha e^{-t} dt$  Euler's Gamma Function

Theorem  $\Gamma(n+1) = n!$  if  $n = 0, 1, 2, \dots$ . But  $\Gamma(x)$  is actually well defined for  $x \in \mathbb{R}$ ; even more it is an holomorphic function of  $z \in \mathbb{C}$ ,  $\Gamma(z)$ . There are singularities, but they are in the negative half-plane  $\operatorname{Re}(z) < 0$



Punchline (clou)

$$\mathcal{L}(t^\alpha) = \frac{\Gamma(\alpha+1)}{s^{\alpha+1}}$$

ex.  $\mathcal{L}(\sqrt{t}) = \mathcal{L}(t^{1/2}) = \frac{\Gamma(3/2)}{s^{3/2}} = \frac{\alpha}{\sqrt{s^3}}$

Where  $\alpha = \int_0^{+\infty} t^{1/2} e^{-t} dt$

PROPERTIES of L.T.

$$\mathcal{L}[e^{at} f(t)](s) = F(s-a)$$

$$\mathcal{L}[f(at)](s) = \frac{1}{a} F\left(\frac{s}{a}\right)$$

$$\mathcal{L}(f(t-T)) = e^{-sT} F(s)$$

$$\mathcal{L}(t^m f(t))(s) = (-1)^m F^{(m)}(s)$$



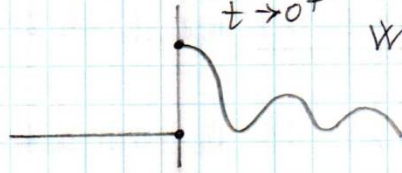
Derivative property (very important)

(★)  $\boxed{\mathcal{L}[f'(t)] = sF(s) - f(0^+)}$

$\lim_{t \rightarrow 0^-} f(t) = 0$  because  $f(t) = 0$  if  $t < 0$   
 $\lim_{t \rightarrow 0^+} f(t)$  can be  $a \neq 0$   
 we call  $a = f(0^+)$

Proof

$$\begin{aligned} \mathcal{L}(f'(t))_{(s)} &= \int_0^{+\infty} f'(t) e^{-st} dt = \\ &= \left[ f(t) e^{-st} \right]_{t=0}^{t=+\infty} + s \int_0^{+\infty} f(t) e^{-st} dt = sF(s) - f(0^+) \end{aligned}$$



(★★)  $\boxed{\mathcal{L}(f^{(m)}(t))_{(s)} = \underbrace{s^m F(s)}_{\text{MAIN TERM (like F.T.)}} - s^{m-1} f(0^+) - s^{m-2} f'(0^+) - \dots - f^{(m-1)}(0^+)}$

Remark Because of this derivative property, the Laplace Transform is well-adapted to solving ODE linear order  $n$  with a Cauchy problem with initial conditions in  $0$ .

(\*)  $a_m y^{(m)} + a_{m-1} y^{(m-1)} + \dots + a_1 y' + a_0 y = f(t) \quad t \in (a, b) \subset \mathbb{R}$

cauchy's  $m$  initial conditions  $\left\{ \begin{array}{l} \text{looking for } y(t) \text{ satisfying (*) and} \\ y(0) = c_0 \quad y'(0) = c_1 \quad y''(0) = c_2 \quad \dots \quad y^{(m-1)}(0) = c_{m-1} \end{array} \right.$

Procedure: take Laplace Transform of both sides of (\*),

get  $Y(s) \cdot \underbrace{(\text{polynomial in } s)}_{P(s)} = F(s)$

$\Rightarrow Y(s) = \frac{F(s)}{P(s)}$  explicit formula for  $\mathcal{L}(y(t))$ , where we have already used the Cauchy  $m$  initial conditions.

Final step  $\mathcal{L}^{-1}\left(\frac{F(s)}{P(s)}\right) = y(t)$  unique solution

There is a general formula to compute  $\mathcal{L}^{-1}$ , but it involves line integrals in  $\mathbb{C}$  (Key words: residues, contour integration, Cauchy's Theorem):



## Inversion Formula

$$f(t) = \frac{1}{2\pi i} \int_{\sigma - i\infty}^{\sigma + i\infty} F(s) e^{st} ds$$

(N.B. in principle, you can invert any  $F(s)$  holomorphic with this formula; we will not use it in this 5<sup>th</sup> course)

If  $F(s)$  is of a particular type (e.g. a rational function  $\frac{p(s)}{q(s)}$  with  $p, q$  polynomials),

It is possible to compute  $f(t) = \mathcal{L}^{-1}(F(s))$  using tables plus properties of  $\mathcal{L}$ .

We have defined on  $\mathbb{R}$   $f * g(x) = \int_{-\infty}^{+\infty} f(x-y)g(y) dy$   
convolution of  $f$  and  $g$ .

In the F.T. theory, we have seen that  $(f * g)^{\wedge}(\xi) = \hat{f}(\xi) \hat{g}(\xi)$

In Laplace Transform theory we also have  $\mathcal{L}[f * g](s) = F(s)G(s)$   
but we need to make an observation, because  $f(t)$  and  $g(t)$

by assumption are  $= 0$  for  $t < 0$

$$\int_{-\infty}^{+\infty} f(x-y)g(y) dy = \int_0^{+\infty} \underbrace{f(x-y)}_{\substack{\text{now observe this other factor} \\ \text{when } x-y < 0 \\ \text{i.e. } x < y}} g(y) dy$$

$$= \int_0^x f(x-y)g(y) dy$$

Book, page 89 has a small table of Laplace Transform.

Google: table of Laplace Transforms

For future reference: there will be cases where we will need to compute  $\mathcal{L}\left[\frac{p(s)}{q(s)}\right]$ . It will be necessary to know the

theory of partial fractions. There are different level of complexity depending on the denominator  $q(s)$ .



Solve  $q(s) = a(s-s_1)(s-s_2)\dots(s-s_m)$

4 levels:

(1)  $q(s) = 0$  has  $n$  solutions real and distinct:

$$\frac{p(s)}{q(s)} = \frac{A_1}{(s-s_1)} + \frac{A_2}{(s-s_2)} + \dots + \frac{A_m}{(s-s_m)}$$

(2)  $q(s) = 0$  has real sol's but there are multiplicities.

(3)  $q(s) = 0$  has simple pairs of conjugate complex sol's.

(remember that if  $q(s)$  has real coeff's and complex roots, these roots appear in conjugate pairs)

(4) complex conjugate with multiplicities...

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$$\mathcal{L} \left( \frac{t^{m-1} e^{at}}{(m-1)!} \right) = \frac{1}{(s-a)^m} \quad a \in \mathbb{C} \text{ (complex constant)}$$

becomes a complex translation

Proof We have proven already  $\mathcal{L}(t^n) = \frac{n!}{s^{n+1}}$

$$\mathcal{L}(t^{m-1}) = \frac{(m-1)!}{s^m}$$

$$\mathcal{L} \left( \frac{1}{(m-1)!} t^{m-1} \right) = \frac{1}{s^m}$$

by linearity  $\leftarrow$  instead of  $s$  put  $s-a$  and get the result

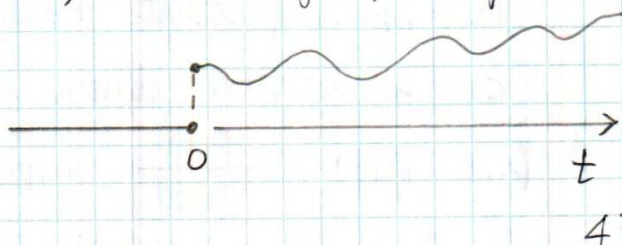
$$\mathcal{L}(e^{at} f(t)) = F(s-a) \quad (\text{Q.E.D.})$$

translation property  $\longrightarrow$

Note the set  $E$  of Laplace-transformable functions satisfies:

$$f(t) : (-\infty; +\infty) \rightarrow \mathbb{C} \text{ (maybe } \mathbb{R}) \text{ with } f(t) = 0 \text{ for } t < 0$$

{  $f(t)$  could be growing }  
 { BUT not too much }



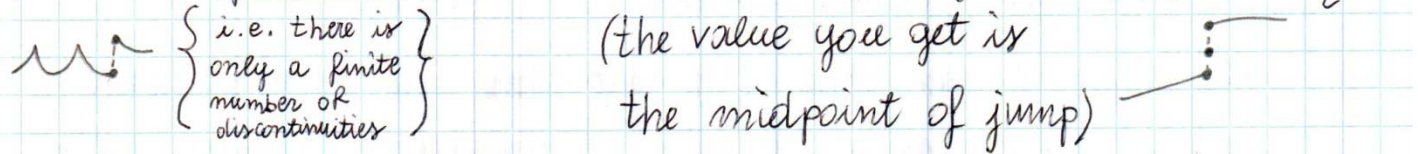


... of ...

$\exists a \in \mathbb{R}$  such that  $f(t) e^{-at} \in L^1(\mathbb{R})$  if  $\text{Re}(a) > \alpha$

(for example  $f(t) = \text{polynomial}$  are OK

$f(t) = e t^3$  not OK)

$f(t)$  is piecewise  $C^1(\mathbb{R})$ ; if there is a jump  $f(x) = \frac{f(x+) + f(x-)}{2}$   
  
 i.e. there is only a finite number of discontinuities (the value you get is the midpoint of jump)

Theorem If both  $f(t)$  and  $p(t) = \int_0^t f(u) du$  are in  $E$   
 then  $\mathcal{L}[p(t)] = \frac{1}{s} F(s)$  (N.B.  $p(0) = 0$ )  
 $\mathcal{L}(f(t))_{(s)}$

Proof:  $\mathcal{L}(p'(t)) = \mathcal{L}(f(t)) = s P(s) - p(0+)$   
 $F(s)$   $P(s) = \mathcal{L}(p(t))$

$$F(s) = s P(s) \quad \frac{1}{s} F(s) = P(s) \quad (\text{Q.E.D.})$$

Theorem (No proof) If  $f(t)$  and  $g(t) \in E$ , then also  $f * g_{(t)} \in E$

Also:  $f * g_{(t)} = \int_{-\infty}^{+\infty} f(y) g(t-y) dy =$   
 $= \int_0^t f(y) g(t-y) dy$

and  $\mathcal{L}(f * g) = \mathcal{L}(f) \mathcal{L}(g) = F(s) G(s)$

(convolutions appear frequently in resolution of D.E.'s)

Suppose  $G(s) = \sum_j \frac{A_j}{(s-a_j)^{m_j}}$  then  $g(t) = \sum_j A_j \frac{t^{m_j-1} e^{a_j t}}{(m_j-1)!}$   
 $\mathcal{L}(g(t))$  (easy consequence of the property we've seen)

This is important because proper rational functions can be written down in this way (partial fractions).

(i.e.  $g(t) = \frac{p(t)}{q(t)}$  where  $p, q$  polynomials and the degree of  $p(t)$  is  $<$  degree of  $q(t)$ )



As you know very well, any rational function is equal to a polynomial plus a proper rational function.

Example: 
$$\frac{3t^3 - t^2 + 1}{t^2 - 1}$$
  
 non-proper rational function

$$\begin{array}{r|l} 3t^3 - t^2 + 1 & t^2 - 1 \\ -3t^3 + 3t & 3t - 1 \\ \hline -t^2 + 3t + 1 & \\ +t^2 & \\ \hline 3t & \end{array}$$

REMAINDER

$$\frac{3t^3 + 1 - t^2}{t^2 - 1} = \frac{3t}{t^2 - 1} + 3t - 1$$

proper rational function

Auxiliary theorem (5.3.9) (DON'T USE WHEN YOU HAVE MULTIPLE ROOTS!)

If  $G(s)$  is a proper rational function  $G(s) = \frac{P(s)}{Q(s)}$   
 (degree  $P <$  degree  $Q$ )  
 ( $P, Q$  polynomials with real coeff's)

Call  $g(t) = \mathcal{L}^{-1}(G(s))$ ; then (1) to a simple zero  $a$  of  $Q(s)$  corresponds in  $g(t)$  the (additive) term  $\frac{P(a)}{Q'(a)} e^{at}$ ;

(2) to a conjugate (simple) pair  $a \pm iw$  of zeros of  $Q(s)$  corresponds in  $g(t)$  the term  $e^{at} (A \cos wt - B \sin wt)$

where  $A$  and  $B$  are real numbers computable from

$$A + iB = 2 \left[ \frac{P(s)}{Q'(s)} \right]_{s = a + iw}$$

(3) (almost obvious) If  $Q(s) = Q_1(s) Q_2(s)$ , with  $Q_1$  and  $Q_2$  polynomials, and if  $Q_1(a) = 0$ , then

$$Q'(a) = Q'_1(a) Q_2(a)$$

Example:  $G(s) = \frac{s}{(s+3)(s^2+4s+5)}$

{ would be more difficult if we had the 3rd deg denominator not factorized

By the auxiliary th. to the zero  $a = -3$  of our denominator corresponds in  $g(t) = \mathcal{L}^{-1}(G(s))$  the term  $\frac{P(-3)}{Q'(-3)} e^{-3t} =$



$$= \frac{-3 e^{-3t}}{[\lambda^2 + 4\lambda + 5]_{\lambda = -3}} = \frac{-3}{9 - 12 + 5} = -\frac{3}{2} e^{-3t}$$

The polynomial  $\lambda^2 + 4\lambda + 5$  has zeros  $-2 \pm \sqrt{2^2 - 5} = -2 \pm i$   
(pair of conjugate non-real zeros) (case (2) of aux. th.)

then to them correspond in  $g(t)$  the term

$$e^{-2t}(A \cos t - B \sin t) \quad \begin{cases} a = -2 \\ \omega = 1 \end{cases}$$

$$\text{Where } A + iB = 2 \left[ \frac{P(\lambda)}{Q'(\lambda)} \right]_{\lambda = -2+i} = 2 \left[ \frac{\lambda}{(\lambda+3)(2\lambda+4)} \right]_{\lambda = -2+i} =$$

$$= 2 \left[ \frac{-2+i}{(-2+i+3)(-4+2i+4)} \right] = 2 \frac{(-2+i)(1-i)}{(1+i)2i(1-i)} = \frac{-1+3i}{2i} \frac{(-i)}{(-i)} =$$

$$= \frac{3+i}{2} = \frac{3}{2} + \frac{1}{2}i \Rightarrow \begin{cases} A = 3/2 \\ B = 1/2 \end{cases}$$

$$\Rightarrow g(t) = -\frac{3}{2} e^{-3t} + e^{-2t} \left( \frac{3}{2} \cos t - \frac{1}{2} \sin t \right)$$

this is the inverse Laplace transform computed without the inversion formula (that involves complex integrals...).

Ex. 2)

$$\begin{cases} y'' - y = 2e^t \\ y(0) = 2 \\ y'(0) = 1 \end{cases}$$

ODE linear, 2<sup>nd</sup> order, constant coeff's  
not homogeneous

(N.B. the ODE by itself has  $\infty^2$  sol's  
depending on  $c_1$  and  $c_2$  arbitrary

constants BUT the 2 Cauchy

initial conditions make the sol. unique

WE WANT TO SOLVE  
THIS PROBLEM USING  
LAPLACE TRANSFORM

$$\mathcal{L}(y^{(n)}(t)) = \lambda^n Y(\lambda) - \lambda^{n-1} y(0^+) - \lambda^{n-2} y'(0^+) - \lambda^{n-3} y''(0^+) - \dots$$

IN OUR CASE:

$$\underbrace{\lambda^2 Y(\lambda) - 2\lambda - 1}_{\mathcal{L}(y(t))} - Y(\lambda) = \frac{2}{\lambda - 1} \} \mathcal{L}(2e^t)$$

$\left\{ \begin{array}{l} \text{N.B. this is a} \\ \text{1st degree equation} \\ \text{in } Y(\lambda) \end{array} \right.$



$$(x^2 - 1) Y(x) = \frac{2}{x-1} + 2x + 1 = \frac{2(2x+1)(x-1)}{x-1} \quad m=2$$

$$Y(x) = \frac{2x^2 - x + 1}{(x+1)(x-1)^2} \stackrel{(*)}{=} \frac{A}{x+1} + \frac{B}{x-1} + \frac{C}{(x-1)^2}$$

proper rational function of  $x$

partial fractions

In general, in the partial fractions expansions, to a real root  $\alpha$  of multiplicity  $m$  correspond

$$\frac{B_1}{x-\alpha} + \frac{B_2}{(x-\alpha)^2} + \frac{B_3}{(x-\alpha)^3} + \dots + \frac{B_m}{(x-\alpha)^m}$$

The case of multiple roots is not included in the aux. th., but...

(\*) is an equality between rational functions, true  $\forall x \in \mathbb{C} \setminus \{\text{root of denom.}\}$ . We can transform (\*) into (\*\*) an equality

of polynomials:  $2x^2 - x + 1 = A(x-1)^2 + B(x+1)(x-1) + C(x+1)$  (\*)

One way to compute  $A, B, C$  would be to expand the 2nd degree polynomial on the r. h. s. of (\*\*) and equate coeff.  $x$ ; this algorithm is OK for degree 2 but it becomes worse and worse as the degree gets higher. That's why we'll see another algorithm.

$$(**) = A(x^2 - 2x + 1) + B(x^2 - 1) + C(x + 1) = (A+B)x^2 + (-2A+C)x + A-B+1$$

This gives a linear system:

$$\begin{cases} A+B=2 \\ -2A+C=-1 \\ A-B+C=1 \end{cases} \quad \begin{array}{l} \text{linear system of} \\ 3 \text{ eq's in } 3 \\ \text{unknowns } A, B, C \end{array}$$

$$\begin{array}{r} 2A+2C=4 \\ -2A+C=-1 \\ \hline 3C=3 \end{array} \quad \begin{array}{l} -2A=-2 \\ A=1 \\ C=1 \end{array}$$

$$B = A + C - 1 = 1 + 1 - 1 = 1$$

This method "sucks" if degrees are high (OK for 2x2 or 3x3 systems)



Other method:

Substitute in (\*\*) the roots of the initial denominator:

$$\underline{\gamma = -1} \quad 2(-1)^2 - (-1) + 1 = A(-2)^2 + \cancel{B \cdot 0} + \cancel{C \cdot 0}$$

$$4 = 4A \Rightarrow A = 1$$

$$\underline{\gamma = +1} \quad 2 - 1 + 1 = C(1+1) \quad 2 = 2C \Rightarrow C = 1$$

Because of the multiplicity  $m = 2$  we run out of values to use...

Use (\*\*\*) which is the  $\frac{d}{d\gamma}$  of (\*\*):

$$4\gamma - 1 = 2A(\gamma - 1) + 2B\gamma + C = 2(\gamma - 1) + 2B\gamma + 1$$

$$\underline{\gamma = 1} \quad 4 \cdot 1 - 1 = 2B + 1 \quad 4 = 2B + 2 \quad 2 = 2B$$

$$B = 1$$

To be complete, we should also give an algorithm to find the partial fraction constants when there are multiple  $\alpha \pm i\beta$ .  
WE SKIP IT.

We have  $Y(\gamma) = \frac{1}{\gamma+1} + \frac{1}{\gamma-1} + \frac{1}{(\gamma-1)^2}$ ; now using tables

$$\text{we get: } y(t) = \mathcal{L}^{-1}(Y(\gamma)) = \underbrace{e^{-t} + e^t}_{\text{hom.}} + \underbrace{te^t}_{\text{forcing term}}$$

in the classical way